

IN THE SPECIFICATION:

Please amend paragraph [0025] as follows:

First, a left half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PL1 on a left side of the handle holder 19 has a mass of mL1 (hereinafter referred to as "left handle mass mL1"), while the left grip 20 has a mass of mL2 (hereinafter referred to as "left grip mass mL2"). Thus, the left side has a mass of mL3 which is a sum of the left handle mass mL2 and the left grip mass mL2 ($mL3 = mL1 + mL2$). The sum mL3 of the left side has a center of gravity as at GL. The present invention is characterized in that the left grip 20 is mounted to the handle 19 by a screw 24 at ~~only~~ a ~~single~~ mounting portion 25 (see Figs. 5A and 5B) substantially at its center of gravity GL corresponding to the left side mass mL3 which is a sum of the left handle portion mass mL1 and the left grip mass mL2, or at a position proximate thereto.

Please amend paragraph [0026] as follows:

Now, a right half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PR1 on a right side of the handle holder 19 has a mass of mR1 (hereinafter referred to as "right handle mass mR1"), while

the right grip 39 has a mass of $mR2$ (hereinafter referred to as "right grip mass $mR2$ "). Thus, the right side has a mass of $mR3$ which is a sum of the right handle mass $mR1$ and the right grip mass $mR2$ ($mR3 = mR1 + mR2$). The sum $mR3$ of the right side has a center of gravity as at GR. The present invention is characterized in that the right grip 30 is mounted to the handle 18 by a screw 24 at ~~only~~ a ~~single~~ mounting portion 25 substantially at its center of gravity GR corresponding to the right side mass $mR3$ which is a sum of the right handle portion mass $mR1$ and the right grip mass $mR2$, or at a position proximate thereto.

Please amend paragraph [0033] as follows:

As shown in FIG. 5A, the grip 20 includes two grip halves between which the handle 18 is held, with a first grip half 21 and a second grip half 22 mating with one another and fixed to the handle 18 by upper and lower fastener members in the form of screws 23, 24. The left grip 20 has a plurality of escape portions 29, formed in an area except for the mount portions 25, which is mounted to the handle 18 with the lower screw 24 at the center GL (see FIG. 4) of gravity of the sum $ML3$ of left mass, to preclude the other remaining portion 26 from being brought into contact with the handle 18.